

でのご使用は避けて下さい。

対象物の材質、形状によって測定できない場合や精度が出ない 場合があります。 (鏡面状の材質、透明な材質、反射率の極端に小さい材質。スポッ ト径よりも小さな対象物、曲率の小さな対象物、大きく傾斜し た対象物など)。

ご承諾事項

#### (4)配線について

・高圧線、動力線と形Z4W-V25Rの配線は別配管として下さい。 同一配管あるいは同一ダクトで行いますと誘導を受け、誤動作 あるいは破損の原因となることがありますので避けてください。

#### (5)その他

対象物に色、材質が極端に違う境界線がある場合は、センサの取 り付け方向により測定値に誤差を生じます。このような場合は図 のようにセンサの取り付け面を境界線と平行になるよう設置すれ ば、誤差を最小にすることができます。



(6)DARK出力	
測定対象物カ	「ない場合や対象物からの反射率が小さい場合など、
センサ内の演	資算処理に必要な光量が不足している場合に出力しま
す。	

- ・光量不足の時:ON(光量表示LEDが赤色点灯)
- 光量適正の時:OFF

#### (7)レンジ表示LED

- センサ前面と対象物の間の距離が測定範囲内のとき、緑色点灯 します。
- センサ前面と対象物の間の距離が測定範囲外のとき、赤色点灯 します。
- ・受光量不足(DARK出力ON、光量表示LEDが赤色点灯)のと きは測定範囲内の物体有無にかかわらず消灯になります。

#### (8)光量表示LED

- ・受光光量を示すLEDでセンサ前面と対象物の間の距離が測定範 囲内のとき、このLEDが緑色点灯または、消灯していれば測定 が可能です。
- センサの前方に対象物がないとき、あるいは受光量不足で測定 できないとき、赤色点灯します。
- ・本センサの使用開始時、センサの測定範囲内に対象物があり、 光量表示LEDが緑色点灯している状態であれば、安心してお使 いいただけます。
- 光量表示LEDが消灯している状態は、内部回路の動作に支障の ない範囲であることを示し、計測動作にはさしつかえありませ
- 使用開始時、緑色点灯であっても、長期間使用すると測定範囲 内に対象物があっても消灯になることがありますが、故障では ありません.



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# Model Z4W-V25R

## **INSTRUCTION SHEET**

Thank you for selecting OMRON product. This sheet primarily describes precautions required in installing and operating the product. Before operating the product, read the sheet thoroughly to acquire sufficient knowledge of the product.

For your convenience, keep the sheet at your disposal.

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## PRECAUTIONS FOR SAFE USE

- (1)Choose an installation place, whenever possible, so that the filter on the sensor front is free from dust and oil droplets If by any chance the filter gets dirty,
- DBlow off dusty particles, if large, with a camera lens blower. (Never breathe out.)
- 2)Gently wipe off dusty particles, if small, with soft cloth (lens cleaner or the like)slightly dampened with alcohol.
- \*Do not wipe clean too hard. Scratched filter may cause malfunction.

## (2)Mutual interference

Two Z4W-V25R displacement sensors can be mounted close to each other without causing any mutual interference. Take the following precautions, though,

Parallel or side-by-side mounting is possible. If they are placed aslant, however, be careful not to allow one's light spot to come in the other's view. This might cause mutual interference.



(Combination with other sensors)

If the displacement sensor is used with other types of sensors (e.g. photoelectric switch), make their optical axes at right angles to each other.



(3)Operating environment

- · Do not expose the sensor to strong external interference light (laser beam, arc welding spark, etc.)or to strong electromagnetic field.
- · The sensor does not guarantee accurate measurement or any measurement at all depending on materials or configurations of objects(mirror-smooth surface, transparent, very small reflectance. smaller than light spot diameter. too small curvature, steep slope, etc.).

## PRECAUTIONS FOR CORRECT USE

(1)Mounting Place the displacement sensor, whenever possible, so that the optical axis is at right angles to the measuring face of an object (with the sensor's light emitting face and the object's measuring face parallel to each other).

It is advisable to keep the sensor front and the object's measuring face at the measuring center distance (25mm).



\*Temporarily tighten the screws. Tighten them up after adjusting the optical axis.

## (2)Wiring

Connect the cores of the sensor cable end to the relevant de vice.

Do not turn on any power. Refer carefully to the markings on the sensor side and the wiring diagram to make correct connections.

## (3)Conversion to voltage output (1 to 5V)

The Z4W-V25R is of current output type with 4 to 20mA. Using the accompanying 250-ohm resistor, the sensor output may be voltage of 1 to 5V. Make connections as shown below.



Keep the resistance below 300 ohms if any other resistor is used

#### (4)Adjusting the optical axis

When the power is turned on, the displacement sensor is activated to send red light from the light emitting face. Move the sensor so that the light spot falls on the object's measuring face. If not all the spot is on the face, detection error may result.



Now tighten up the screws to fix the sensor.

(5)Analog output (4 to 20mA current output)

When the object is within the measuring center distance (reference: $25 \pm 1$  mm), a 12mA output is given. As the object comes nearer the sensor, the output decreases (12mA, 11mA, 10mA,...). With the object going farther away, the output increases (12mA. 13mA, 14mA,...). The output displacement for the object to shift 1mm is 2mA in the range of 4 to 20mA.

The saturation levels are 20.5 to 26mA for the upper limit and 1 to 3.5mA for the lower limit. This saturation varies slightly with products. The analog output shows the upper saturation level if there is no object in place or if the reflectance of an object is too small for the light to come back to the sensor (DARK condition).



## (6)DARK output

This output is given when the light quantity is too small for the sensor to carry out operating; no object or too small reflect-

#### SPECIFICATIONS

Item Model		Z4W-V25R	
Measuring range		±4mm	
Measuring center distance		25±1mm	
Light source		Red LED	
Spot diameter		\$\$ 2mm(at measuring center distance)	
Resolution Note1		10 <sup>µ</sup> m(in standard condition)	
Linearity	Note2	±3%FS	
Response speed Note3		5ms	
Temperature characteristic		±0.3%FS/°C	
Warm-up time		3min.(within 土1% from stable level)	
LED indictor	STABILITY lamp	Stable operating range: Green Operating range: Off Light quantity short(DARK):Red	
	RANGE lamp	In measuring range: Green Out of measuring range: Red	
Output	Analog output	$4mA$ to $20mA/\pm 4mm$ (lord impedance:Max. $300 \Omega$ )	
	DARK output	NPN open collector output (Max. AC30V, 50mA) Residual voltage:1V or less	
External interference light		3000lx(white light)	
Vibration resistance		10Hz to 55Hz (double amplitude:15mm), 15 min each for 3 directions, 2 sweeps	
Shock resistance		50G, 3 times each for 3 directions (vertical, lateral and traverse)	
Supply power		DC12 to 24V±10%, ripple:10% or less	
Power consumption		80mA or less	
Weight		About 150g(with 5m cable), about 50g (without cable)	
Ambient operating temperature		-10 to +55°C(no freezing)	
Ambient storage temperature		-25 to +65°C(no freezing)	
Ambient operating humidity		35 to 85%RH(no condensation)	
Protective design		IEC Standard IP66	
Cable length		5m	

Note 1 : Resolution

Peak-to-peak conversion of analog displacement output (under standard measuring conditions: white alumina ceramic object at measuring center distance)



Note 2 : With white alumina ceramic object. Accuracy may depend on types of objects. Note 3 : Responce speed

Rise and fall times (10  $\sim$  90%) of analog displacement output displacement changes when

## ACCESSORIES

Name	Q'ty
Fixture	1 pc.
Mounting screw (M4×12)	2 pcs.
Flat washer (M4)	2 pcs.
Resistor, 250Q, 1/2W	1pc.
Operating instructions	1 copy

Cable length 5





## CONNECTION / OUTPUT CIRCUIT DIAGRAMS



4 to 20m/ Linear co unit, etc Note 2 : Connect the leads correctly. Wrong wiring may result in

DC12 to 24\

OV

**DUTER DIMENSIONS** 

Note 3 : Do not turn on any power while wiring.

## ■TYPICAL CONNECTIONS WITH LINEARITY I.D. UNIT AND LINEAR SENSOR CONTROLLER

## • With the Z4W-DD1C





Note 1 : Keep the short-circuit lug attched in place when no sync input is used.

Note 2 : With the Z4W being connected, "----" or "FFFF" appears in the display of the S3A2 while the object is out of the Z4W's measuring range.

Suitability for Use





Note 1 : The fixture may be used on Face A instead.

Load drive power (DC30V or less)

-DC12 to 24V

#### (4)Wiring

• Run the Z4W-V25R cable in an independent conduit. If it is laid through the same conduit or duct as a high-tension or power cable, the cable is affected by induction. This may cause malfunction or damage.

#### (5)Others

If the object has a boundary between quite different colors or materials, measurements may be wrong depending on the position of the sensor. In such a case, position the sensor in parallel with the boundary, as shown below, to minimize possible errors.



ance on the object face, for example

- · Light quantity too small: ON (The STABILITY lamp lights up in red.)
- · Light quantity appropriate: OFF

#### (7)RANGE lamp

- · Lights up in green when the distance between the sensor front and the object is within the measuring range.
- · Lights up in red when the above-mentioned distance is without the measuring range.
- · Goes out, whether or not the object is within the measuring range, when the received light quantity is too small (DARK output on. STABILITY lamp in red).

#### (8)STABILITY lamp

- The sensor is ready to measure when this indicator is green or off. Note that the distance between the sensor front and the object is within the measuring range.
- · This indicator lights up in red if there is no object in front of the sensor or if the received light quantity is too small to measure.
- · Before starting the operation, se if the object is within the sensor's measuring range and this indicator is green. This means that the sensor functions well.
- . If the indicator is off, this means that there is no trouble with the sensor's internal circuitry and that the sensor is okay for measurement
- . The indicator might remain green for a while and go out with the object coming within the measuring range. This is not a trouble.



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